Optimization of femtosecond laser cutting of a biodegradable polymer for medical devices manufacturing

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Abstract—This paper describes the experimental parameters involved in the femtosecond laser micromachining of biodegradable poly(L-lactide) which is frequently used in biomedical applications such as vascular stents or scaffolds. We investigated the influence of laser pulse energy, scanning strategy and number of overscans on the laser cutting throughput. The process parameters that enable reducing a heat affected zone were determined. As a result, the optimal scanning strategy was determined in order to obtain high aspect ratio trenches in a 380µm thick biodegradable polymer sheet.

Over the last decade we have observed the increasing involvement of femtosecond lasers for manufacturing biomedical devices made of biodegradable polymers. A small beam diameter and short pulse duration enable forming complex, submillimeter geometrical shapes in polymers such as vascular stents which cannot be manufactured using traditional techniques e.g. injection moulding or mechanical processing. The shortening of pulse duration below electron cooling time enables reduction of thermal and mechanical damage to the surrounding material. Furthermore, extremely high power density causes multiphoton absorption that allows for processing wide-bandgap dielectrics. Together with high pulse energy in the range of tens of microjoules attainable in modern industrial constructions, femtosecond lasers appear as a perfect tool for efficient machining of polymers.

There are, however, several limitations regarding the use of femtosecond lasers for processing heat sensitive biodegradable polymers. As it was reported previously, laser micromachining with ultrashort pulse lasers can result in thermal load affecting the surrounding material causing its melting, crack formation [1-2] or crystallisation [3]. Nevertheless, heat accumulation appears mainly for a high repetition rate, high pulse energy and multiple scanning cycles. Depending on the relation between laser wavelength, fluence, repetition frequency and pulse overlapping, the process can be designed to be a-thermal [2]. In order to preserve a relatively high process throughput one can apply different strategies such as decreasing pulse overlapping [4] or

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using gas assist [2]. Another issue affecting the processing speed is the reflection and scattering of incident light in a V-shaped groove causing a decrease of the ablation rate with an increasing number of over-scans [5].

This article presents the results of the cutting process optimisation of medical grade poly(L-lactide) (PLLA – RESOMER® L 210 S, Evonik Biomaterials). PLLA is a semicrystalline aliphatic polyester which is transparent in a wide optical window beginning from 250nm up to near infrared. The thickness of an amorphous polymer sheet prepared using a hydraulic press was $380\pm10\mu$ m. The experiments were performed using s laser from Active Fiber Systems Jena with the pulse duration τ =450fs, wavelength λ =515nm and fixed pulse repetition frequency 10kHz. The focal length of the lens was 163mm and the beam diameter in the focal plane was 25µm.

The laser cutting trials were performed in ambient air using a test pattern that consists of six grooves with a length of 1mm and a different width (Fig. 1). The grooves were produced by bidirectional scanning in the y direction each with the hatching distance $10\mu m$.



Fig. 1. Test pattern and scanning routine.

The scanning speed of 100mm/s resulted in 10 μ m pulse spacing along the scan direction. In consequence, the *xy* pulse separation was 10 μ m during all experiments. A different width of grooves was obtained by increasing the number of parallel lines from 2 up to 17.

The width was measured at the top surface. The test pattern was performed using a different laser fluence $1.4 \div 5.2 \text{ J/cm}^2$ and a number of overscans $10 \div 60$.



Fig. 2. The 3D image and profile of test pattern in PLLA obtained for 50 overscans and a fluence of 2.1J/cm².

The profile of grooves presented in Fig. 2 shows that there is strong dependence between the depth and number of parallel lines used, thus the kerf width. The asymmetric profile of a single groove is caused by the direction of scanning from the left side to the right. In order to find optimal parameters for a cutting process it is necessary to investigate the relation between the number of lines and the number of overscans in relation to the applied laser fluence.



Fig. 3. The measured depth of grooves as a function of the number of overscans for a different number of parallel lines at a fluence of 2.9J/cm².

As can be observed in Fig. 3, the depth of grooves/ablation rate saturates with an increasing overscan number for 2 and 5 lines which correspond to 47 and 80μ m kerf width, respectively. The increase of groove width up to 115μ m (8 lines) results in noticeable increase of the ablation rate in a range of $40\div60$ overscans. An interesting effect can be seen for 10 and 20 repetitions where the depth is almost independent of the groove width while for 30 repetitions the number of lines plays an important role. Figure 4 presents data points from the Fig. 3 in relation to the resulting speed of cutting which was calculated as the speed of the scanner 100mm/s divided by

the product of the number of lines and number of overscans. This representation allows one to shorten the processing time and have the desired kerf width. As can be noted, there are limitations regarding the maximum depth which can be achieved using 2, 5 and 8 lines using up to 60 overscans. Nevertheless, the highest cutting speed for the material with a thickness up to 340 μ m can be achieved using 2÷8 parallel lines. The use of 14, 17 lines and 60 overscans allowed us to cut through a 380 μ m polymer sheet. It is worth emphasizing that the taper angle between the cut walls is not considered here.



Fig. 4. The cutting speed for different sets of parameters with an indicated kerf width in relation to the obtained depth.

The cutting speed can be increased by changing the laser fluence, repetition frequency or pulse overlapping. However, a-thermal character of machining has to be preserved. Cutting trials were performed also for different laser fluence values. As shown in Fig. 5, the increase of fluence up to 4.7÷5.2J/cm² enabled cutting through a PLLA sheet using 30 overscans.



Fig. 5. The depth of grooves as a function of laser fluence and the number of lines for 30 overscans.

Ablation rate enhancement is most visible in the case of a higher number of lines $11\div17$. For narrow grooves $2\div8$ the ablation rate saturates faster with increasing power. The cutting speed at the laser fluence F=5.2J/cm² calculated for different scanning strategies is shown in

Fig. 6. An improvement is noticeable in comparison to the maximum process speed obtained with $F=2.9J/cm^2$. There is, however, a limiting factor for increasing pulse energyheat affected zone (HAZ).



Fig. 6. The cutting speed as a function of the depth at a fluence of 5.2J/cm² and marked maximum cutting speed obtained using 2.9J/cm².

We observed that for high fluence and a high number of parallel lines there is an HAZ surrounding the grooves. Nonetheless, it is worth noting that such an effect can be reduced by increasing the length of a groove which would avoid heat accumulation. The HAZ formation was not observed for a number of lines $2\div 5$ at any of used process parameters. The process parameters enabling the highest cutting speed without HAZ formation for certain material thickness are collected in Table 1.



Fig. 7. Heat affected zone observed for 20 overscans and a fluence of 5.2J/cm^2 for an indicated number of lines.

A similar HAZ in PLLA connected with heat accumulation and caused by CO₂ or ArF excimer laser cutting was observed and characterized previously [6-7]. The HAZ visible in Fig. 7 is a result of the increase in material temperature above glass transition temperature (~ 65°C for PLLA) during the process.

As presented in Fig. 8, the cutting of a polymer sheet thicker than 300µm can be considered as inefficient. The processing speed decreases exponentially while the kerf width increases reaching the values which are limiting precision.

Cutting Kerf Number PLLA Number Fluence speed width of thickness of lines $[J/cm^2]$ overscans [mm/s] [µm] 80 5.2 5.00 2 47 10 150 2.50 2 47 5.2 20 250 0.66 5 80 5.2 30 300 0.25 8 115 2.9 50 380 0.15 11 138 2.9 60 6 180 Cutting speed 160 5 Cutting speed [mm/s] Kerf width 140 [mm] 4 120 width 3 100 80 Kerf 2 60 1 40 0 20 0 100 200 300 400 500 PLLA thickness [um]

Fig. 8. The relation between maximum process speed and kerf width for certain PLLA thickness

In comparison to other reports on femtosecond laser cutting of poly(L-lactide) with a single-scan procedure [2], the obtained process speed without gas assist is at least one order of magnitude higher. Despite the femtosecond pulse duration, there is still a need to optimize the process in order to avoid residual heat accumulation especially in the case of heat sensitive medical grade polymers.

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Table 1. Optimal laser machining parameters for HAZ-free cutting of desired PLLA thickness